

M0609

M1509

M1013

M0617

1 /  
+0.1  
5 - 45

( : o, : / )

	M0609	M1509	M1013	M0617
J1	±360° / 150° /s	±360 / 150° /s	±360° / 120° /s	±360 / 100° /s
J2	±360° / 150° /s	±360 / 150° /s	±360° / 120° /s	±360 / 100° /s
J3	±150° / 180° /s	±150 / 180° /s	±160° / 180° /s	±165 / 150° /s
J4	±360° / 225° /s	±360 / 225° /s	±360° / 225° /s	±360 / 225° /s
J5	±360° / 225° /s	±360 / 225° /s	±360° / 225° /s	±360 / 225° /s
J6	±360° / 225° /s	±360 / 225° /s	±360° / 225° /s	±360 / 225° /s

IP54  
6 / 6  
DC25V/ .3A

Ethernet (TCP/IP) Modbus TCP  
RS 232 / Profinet/ USB  
Modbus TCP\*  
490 390 287  
9  
IP 30  
16 / 16  
2 / 2  
DC 24V  
100 - 240 (50 - 60 ) VAC  
6.0  
4.5

IP 40  
264 218 42  
0.8 / 10.1'



Switch on the Future  
**Doosan Robotics**

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doosanrobots.ru doosanrobotics.com





reddot award 2017  
winner



reddot award 2018  
winner





reddot award 2018  
winner

6-

6

## M0609

6 , 0.9  
0.9



Payload : 6 kg  
Reach : 900 mm

## M1509

15  
0.9



Payload : 15 kg  
Reach : 900 mm

## M1013

10  
1.3



Payload : 10 kg  
Reach : 1,300 mm

## M0617

6  
1.7



Payload : 6 kg  
Reach : 1,700 mm



1 Real-time OS  
EtherCAT,

Ethernet, Fieldbus, Serial, etc.



1280 800



Cockpit

5



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